

Matrix	# of Tlen
$1_{4 \times 4}$	1
γ^m	4
$\sigma^{mn} = \frac{i}{2} [\gamma^m, \gamma^n]$	6
$\gamma^m \gamma^5$	4
γ^5	1

Any 4×4 matrix T^{AB} is a linear combination of these.

Note $P_{R,L} = \left(\frac{1 \pm \gamma^5}{2} \right)$ are projection operators onto different subspaces.

$$P_L + P_R = 1, \quad P_L P_L = P_L P_R = 0, \quad P_R^2 = P_R, \quad P_L^2 = P_L$$

The matrices in the above basis either commute or anticommute with γ^5

$$[P^I, \gamma^5] = 0 \quad 1, \sigma^{mn}, \gamma^5 \quad P_L P^I P_R = P_R P^I P_L = 0$$

$$\{P^I, \gamma^5\} = 0 \quad \gamma^m, \gamma^m \gamma^5 \quad P_L P^I P_L = P_R P^I P_R = 0$$

Matrices P^I in our basis are linearly independent + span space of 4×4 matrices. Can write, for example

$$\gamma^a \gamma^b \gamma^c = \sum_I C_I P^I$$

Let's work out this expansion explicitly

First

$$[\gamma^\alpha \gamma^\beta \gamma^\delta, \gamma^\epsilon] = 0$$

So $\gamma^\alpha \gamma^\beta \gamma^\delta$ is a lc of $\gamma^\mu, \gamma^\nu \gamma^\delta$. Also

$$\begin{aligned} D(\Lambda)^{-1} \gamma^\alpha \gamma^\beta \gamma^\delta D(\Lambda) &= \Lambda^\alpha{}_\mu \gamma^\mu \Lambda^\beta{}_\nu \gamma^\nu \Lambda^\delta{}_\rho \gamma^\rho D(\Lambda) \\ &= \Lambda^\alpha{}_\mu \Lambda^\beta{}_\nu \Lambda^\delta{}_\rho \gamma^\mu \gamma^\nu \gamma^\rho \end{aligned}$$

So must transform "as a rank 3 tensor"

$$\begin{aligned} \gamma^\alpha \gamma^\beta \gamma^\delta &= X \eta^{\alpha\beta} \gamma^\delta + Y \eta^{\beta\delta} \gamma^\alpha + Z \eta^{\alpha\delta} \gamma^\beta \\ &\quad + W i \epsilon^{\alpha\beta\gamma\delta} \gamma_\gamma \gamma_\delta + \dots \end{aligned}$$

More terms with $\gamma^\alpha \gamma_\beta +$ no epsilon $\gamma \in \mathbb{R}^n$ with no γ_δ . In fact we can argue there don't occur. Recall under parity

$$\psi \rightarrow \pm \gamma^0 \psi \quad \gamma^0 = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

$$\begin{aligned} \gamma^0 \gamma^i \gamma^j \gamma^k \gamma^0 &= -\gamma^i \gamma^j \gamma^k \\ \gamma^0 \eta^{ij} \gamma^k \gamma^0 &= +\eta^{ij} \gamma^k \gamma^0 \\ &\quad \text{wrong sign} \end{aligned}$$

$$\gamma^0 \epsilon^{ijkl} \gamma_m \gamma^0 = \gamma^0 \epsilon^{ijk} \otimes \gamma_0 \gamma_0 = +\epsilon^{ijk} \gamma_m$$

So Eterms vanish + we have

$$\gamma^\alpha \gamma^\beta \gamma^\delta = X \eta^{\alpha\beta} \gamma^\delta + Y \eta^{\beta\delta} \gamma^\alpha + Z \eta^{\alpha\delta} \gamma^\beta + W i \epsilon^{\alpha\beta\gamma\delta} \gamma_\gamma \gamma_\delta -$$

Symmetrize on α and β : $(\alpha\beta + \beta\alpha)/2$

$$\eta^{\alpha\beta}\gamma^\delta = X\eta^{\alpha\beta}\gamma^\delta + \frac{Y}{2}(\eta^{\beta\delta}\gamma^\alpha + \eta^{\alpha\delta}\gamma^\beta) \\ + \frac{Z}{2}(\eta^{\alpha\delta}\gamma^\beta + \eta^{\beta\delta}\gamma^\alpha) + 0$$

$$\Rightarrow X=1, \quad Y+Z=0$$

Next symmetrize on β and δ

$$\gamma^\alpha\eta^{\beta\delta} = \frac{X}{2}(\eta^{\alpha\beta}\gamma^\delta + \eta^{\alpha\delta}\gamma^\beta) \\ + Y\eta^{\beta\delta}\gamma^\alpha + \frac{Z}{2}(\eta^{\alpha\delta}\gamma^\beta + \eta^{\alpha\beta}\gamma^\delta) + 0$$

$$\Rightarrow X+Z=0, \quad Y=1$$

So we have

$$X=Y=1, \quad Z=-1$$

It only remains to determine W . Pick $\alpha=0, \beta=1, \gamma=2$

$$\gamma^0\gamma^1\gamma^2 = W i \in^{0123} \gamma_3 \gamma_5$$

$$\gamma^0\gamma^1\gamma^2\gamma^3 = W i \gamma_3 \gamma_5 \gamma^3 = -W i \gamma_5$$

$$\Downarrow \\ -i\gamma_5 = -W i \gamma_5 \Rightarrow W=1$$

$$\gamma^\alpha\gamma^\beta\gamma^\delta = \eta^{\alpha\beta}\gamma^\delta + \eta^{\beta\delta}\gamma^\alpha - \eta^{\alpha\delta}\gamma^\beta + i \epsilon^{\alpha\beta\delta\eta} \gamma_\eta \gamma_5$$

There are several other useful identities

$$\text{Tr } \gamma^\alpha \gamma^\beta = \text{Tr } \frac{1}{2} (\gamma^\alpha \gamma^\beta + \gamma^\beta \gamma^\alpha) = \text{Tr } \eta^{\alpha\beta} \mathbb{1} = 4 \eta^{\alpha\beta}$$

Traced an odd # of Gamma matrices vanishes

$$\begin{aligned} \text{Tr } \gamma^{m_1} \dots \gamma^{m_{2n+1}} &= \text{Tr } \gamma^{m_1} \dots \gamma^{m_{2n+1}} \gamma_5 \gamma_5 \\ &= -\text{Tr } \gamma^{m_1} \dots \gamma^{m_{2n}} \gamma_5 \gamma^{m_{2n+1}} \gamma_5 \\ &= (-1)^{2n+1} \text{Tr } \gamma_5 \gamma^{m_1} \dots \gamma^{m_{2n+1}} \gamma_5 \\ &= -\text{Tr } \gamma^{m_1} \dots \gamma^{m_{2n+1}} \end{aligned}$$

move over proper $\text{Tr } AB = \text{Tr } BA$

$$\Rightarrow \text{Tr } \gamma^{m_1} \dots \gamma^{m_{2n+1}} = 0$$

$$\begin{aligned} \text{Tr } \gamma^m \gamma^\nu \gamma^\alpha \gamma^\beta &= 2 \eta^{\alpha\beta} \text{Tr } \gamma^m \gamma^\nu - \text{Tr } \gamma^m \gamma^\nu \gamma^\beta \gamma^\alpha \\ &= 8 \eta^{\alpha\beta} \eta^{m\nu} - 2 \eta^{\beta\nu} \text{Tr } \gamma^m \gamma^\alpha + \text{Tr } \gamma^m \gamma^\beta \gamma^\nu \gamma^\alpha \\ &= 8 \eta^{\alpha\beta} \eta^{m\nu} - 8 \eta^{\beta\nu} \eta^{m\alpha} + 2 \eta^{m\beta} \text{Tr } \gamma^\nu \gamma^\alpha - \text{Tr } \gamma^\beta \gamma^m \gamma^\nu \gamma^\alpha \\ &= 8 \eta^{\alpha\beta} \eta^{m\nu} - 8 \eta^{\beta\nu} \eta^{m\alpha} + 8 \eta^{m\beta} \eta^{\alpha\nu} - \text{Tr } \gamma^m \gamma^\nu \gamma^\alpha \gamma^\beta \end{aligned}$$

$$\Rightarrow \text{Tr } \gamma^m \gamma^\nu \gamma^\alpha \gamma^\beta = 4 [\eta^{\alpha\beta} \eta^{m\nu} + \eta^{m\beta} \eta^{\alpha\nu} - \eta^{\beta\nu} \eta^{m\alpha}]$$

Notation $\not{a} = a_\mu \gamma^\mu$

$$\text{Tr } \not{a} = 0$$

$$\text{Tr } \not{a} \not{b} = 4 a \cdot b$$

$$\text{Tr } \not{a} \not{b} \not{c} \not{d} = 4 [a \cdot b c \cdot d + a \cdot d b \cdot c - a \cdot c b \cdot d]$$

Quantizing Dirac Lagrangian

$$\mathcal{L} = \bar{\psi} (i\partial - m)\psi$$

$$\frac{\delta \mathcal{L}}{\delta \psi} = 0 \Rightarrow (i\partial - m)\psi = 0$$

$$\pi = \frac{\delta \mathcal{L}}{\delta \dot{\psi}} = \bar{\psi} i\gamma^0 = i\psi^\dagger$$

$$H = \int d^3x (\pi \dot{\psi} - \mathcal{L})$$

$$= \int d^3x (i\psi^\dagger \dot{\psi} - i\psi^\dagger \dot{\psi} - i\bar{\psi} \vec{\gamma} \cdot \vec{\nabla} \psi + m\bar{\psi}\psi)$$

$$= \int d^3x (-i\bar{\psi} \vec{\gamma} \cdot \vec{\nabla} \psi + m\bar{\psi}\psi)$$

Heisenberg field solves field eq.

$$(i\partial - m)\psi = 0$$

Try plane wave soln $\psi(x) = u(p) e^{-ip \cdot x}$

$$\text{Note } (i\partial - m)\psi = 0$$

$$\Rightarrow (i\partial + m)(i\partial - m)\psi = 0$$

$$\Rightarrow (-\partial^2 + m^2)\psi = 0$$

So each component obeys KGeq. $\Rightarrow p^2 = m^2$.

To find spinor $u(p)$ must solve

$$(\not{p} - m)u(p) = 0$$

Lets first work in rest frame $p^\mu = \hat{p}^\mu = (m, \vec{0})$

$$(m\gamma^0 - m)u(\hat{p}) = 0$$

$$m \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} u(\hat{p}) = 0$$

$$\Rightarrow u(\hat{p}) = \sqrt{m} \begin{pmatrix} \xi \\ \xi \end{pmatrix}$$

↑
convention

Under rotation \hat{z} transforms like ordinary Pauli spins. $\hat{\xi} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$, $\hat{\chi} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ are usual spin up & spin down spins. Let's get a more general solution by boosting along \hat{z} axis. Recall under boost corresponding to hyperbolic angle ϕ

$$\begin{pmatrix} E \\ p^3 \end{pmatrix} = \begin{pmatrix} \cosh \phi & \sinh \phi \\ \sinh \phi & \cosh \phi \end{pmatrix} \begin{pmatrix} m \\ 0 \end{pmatrix} = \begin{pmatrix} m \cosh \phi \\ m \sinh \phi \end{pmatrix}$$

Can use properties of hyperbolic functions to do it.

$$\sqrt{m} \cosh(\phi/2) = \frac{1}{2} (\sqrt{E+p^3} + \sqrt{E-p^3})$$

$$\sqrt{m} \sinh(\phi/2) = \frac{1}{2} (\sqrt{E+p^3} - \sqrt{E-p^3})$$

Now from our work on the Lorentz Group

$$u(\varphi) = D(\Lambda)u(\hat{\varphi}) = \begin{pmatrix} e^{-(\phi\sigma^3/2)} & 0 \\ 0 & e^{(\phi\sigma^3/2)} \end{pmatrix} u(\hat{\varphi})$$

$$= \exp\left(-\frac{\phi}{2} \begin{bmatrix} \sigma^3 & 0 \\ 0 & -\sigma^3 \end{bmatrix}\right) u(\hat{\varphi})$$

$$= \left[\sum_{n=0}^{\infty} \left(\frac{\phi}{2}\right)^{2n} \frac{1}{(2n)!} I_{4 \times 4} - \sum_{n=0}^{\infty} \left(\frac{\phi}{2}\right)^{2n+1} \frac{1}{(2n+1)!} \begin{pmatrix} \sigma^3 & 0 \\ 0 & -\sigma^3 \end{pmatrix} \right] u(\hat{\varphi})$$

$$= \left[\cosh\left(\frac{\phi}{2}\right) I_{4 \times 4} - \sinh\left(\frac{\phi}{2}\right) \begin{pmatrix} \sigma^3 & 0 \\ 0 & -\sigma^3 \end{pmatrix} \right] u(\hat{\varphi})$$

$$= \sqrt{m} \begin{pmatrix} \cosh\phi/2 & -\sinh\phi/2 \sigma^3 & & 0 \\ & & & \\ & & & \\ 0 & & & \cosh\phi/2 + \sinh\phi/2 \sigma^3 \end{pmatrix} \begin{pmatrix} \xi \\ \xi \end{pmatrix}$$

$$= \sqrt{m} \begin{pmatrix} \left[\cosh\frac{\phi}{2} - \sigma^3 \sinh\frac{\phi}{2} \right] \xi \\ \left[\cosh\frac{\phi}{2} + \sigma^3 \sinh\frac{\phi}{2} \right] \xi \end{pmatrix}$$

$$= \begin{bmatrix} \left\{ \frac{1}{2} (\sqrt{E+p^3} + \sqrt{E-p^3}) - \frac{\sigma^3}{2} (\sqrt{E+p^3} - \sqrt{E-p^3}) \right\} \xi \\ \left\{ \frac{1}{2} (\sqrt{E+p^3} + \sqrt{E-p^3}) + \frac{\sigma^3}{2} (\sqrt{E+p^3} - \sqrt{E-p^3}) \right\} \xi \end{bmatrix}$$

There is a much more compact way to write the Dirac

$$\sigma^m = (1, \sigma^j), \quad \bar{\sigma}^m = (1, -\sigma^j)$$

$$p \cdot \sigma = E - \vec{\sigma} \cdot \vec{p}, \quad p \cdot \bar{\sigma} = E + \vec{\sigma} \cdot \vec{p}$$

Now put row after square

$$\begin{aligned} & \left\{ \frac{1}{2} (\sqrt{E+p^3} + \sqrt{E-p^3}) - \frac{\sigma^3}{2} (\sqrt{E+p^3} - \sqrt{E-p^3}) \right\}^2 \\ &= \left\{ \sqrt{E+p^3} \left(\frac{1-\sigma^3}{2} \right) + \sqrt{E-p^3} \left(\frac{1+\sigma^3}{2} \right) \right\}^2 \\ &= (E+p^3) \left(\frac{1-\sigma^3}{2} \right) + (E-p^3) \left(\frac{1+\sigma^3}{2} \right) \\ &= E - p^3 \cdot \sigma^3 = p \cdot \sigma \end{aligned}$$

Similarly square of second row $\rightarrow p \cdot \bar{\sigma}$

$$u(p) = \begin{pmatrix} \sqrt{p \cdot \sigma} \xi \\ \sqrt{p \cdot \bar{\sigma}} \xi \end{pmatrix} \leftarrow \text{true / general!}$$